RESULTS ACHIEVED WITHIN THE FRAMEWORK OF
THE EU RESEARCH PROJECT:
CATCH, EFFORT, AND ECOSYSTEM IMPACTS OF FAD-FISHING (CECOFAD)

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SUMMARY

The European project CECOFAD collected unofficial information related to DFAD-fishing (e.g., systems used for positioning buoys at-sea). The definitions of variables required for evaluating DFAD-fishing activities that should be continuously recorded in logbooks were reviewed. The total number of DFADs deployed in the Atlantic and Indian oceans over the last ten years were estimated based on information provided by the French fleet and extrapolated to the other purse seiners. The relationship between the number of active DFADs and the catch per Spanish purse seiner was explored. The standardization of CPUE by a LASSO regression model was limited to non-standard explanatory variables provided by the French fleet only. The needs to collate the links between each support vessel and its associated purse seiners and the number of active DFADs per vessel was highlighted. As an alternative to CPUE, direct abundance indices from echo sounder buoys attached to DFADs in the Spanish fleet were investigated. The analysis of the French GPS buoys showed that around 10% of the trajectories ended with a "beaching event", with significant portions occurring in vulnerable areas. Simulations were conducted to evaluate the consequences of introducing wide area, six-month moratoria on DFAD sets on tropical tuna and bycatch.

RÉSUMÉ

Le projet européen CECOFAD a recueilli des informations officieuses relatives à la pêche sous DCPd (p.ex. systèmes utilisés pour le positionnement des bouées en mer). On a révisé les définitions des variables requises pour évaluer les activités de pêche sous DCP dérivants qui devraient être consignées en permanence dans les carnets de pêche. Le nombre total de DCP dérivants déployés dans les océans Atlantique et Indien au cours des dix dernières années a été estimé à partir des renseignements fournis par la flottille française et extrapolés aux autres senneurs. On a exploré la relation entre le nombre de DCPd actifs et la prise par les senneurs espagnols. La standardisation de la CPUE par un modèle de régression LASSO s'est limitée aux variables explicatives non standard fournies uniquement par la flottille française. On a souligné le besoin de rassembler les liens entre chaque navire de support et ses senneurs associés et le nombre de DCP dérivants actifs par navire. Comme alternative à la CPUE, on a étudié les indices directs d'abondance au moyen de balises échosondeur fixées aux DCP dérivants dans la flottille espagnole. L'analyse des bouées GPS françaises a révélé qu'environ 10% des trajectoires se terminent par un échouage, une grande proportion ayant lieu dans des zones vulnérables. Des simulations ont été réalisées pour évaluer les conséquences pour les thonidés tropicaux et les prises accessoires de l'introduction de moratoires sur les opérations sous DCP dérivants sur une période de six mois et sur une vaste zone.

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RESUMEN

El Proyecto europeo CECOFAD recopilaba información no oficial relacionada con la pesca sobre DCP-D (por ejemplo, los sistemas utilizados para posicionar las boyas en el mar). Se revisaron las definiciones de las variables requeridas para evaluar las actividades de pesca sobre DCP-D, que deberían ser continuamente consignadas en los cuadernos de pesca. Se estimó el número total de DCP-D plantados en los océanos Índico y Atlántico en los últimos diez años basándose en la información proporcionada por la flota francesa y extrapolada a otras flotas de cerco. Se exploró la relación entre el número de DCP-D activos y la captura de los cerqueros españoles. La estandarización de la CPUE por medio de un modelo de regresión LASSO se limitó a variables explicativas no estándar facilitadas solo por la flota francesa. Se destacó la necesidad de recopilar los vínculos entre cada buque de apoyo y sus cerqueros asociados y el número de DCP-D activos por buque. Como alternativa a la CPUE, se investigaron índices directos de abundancia a través del uso de boyas con ecosonda unidas a los DPC-D en la flota española. El análisis de las boyas GPS francesas demostró que aproximadamente el 10% de las trayectorias terminaba con un "varamiento", con una parte importante de ellos produciéndose en zonas vulnerables. Se llevaron a cabo simulaciones para evaluar las consecuencias sobre los túnidos tropicales y la captura fortuita de introducir una moratoria de seis meses a los lances sobre DCP-D en una zona amplia.

KEYWORDS

Tropical tuna purse seine fishery, DFAD technology, GPS buoys trajectories, CPUE standardization, LASSO regression model, echo sounder abundance estimate, bycatch, beaching event, DFAD-moratorium simulations, Species diversity

Introduction

This document was originally presented at the 2nd Meeting of the Ad Hoc Working Group on FADs. The objectives of the EU CECOFAD project were: (1) to provide insights into the definition of the fishing effort associated with drifting fishing aggregating devices (DFADs) that accounts for the implementation of new technology influencing catchability, (2) to introduce the factors describing the technology associated with this fishing mode into the standardization of the European tropical tuna purse seiner catch-per-unit-of-effort (CPUE) and (3) to provide information on catch composition around FADs and estimate the impacts on other marine organisms (e.g. bycatch of sharks, rays and turtles).

To achieve these objectives, CECOFAD was organized into 4 Work Packages (WPs), as follows:

- WP 1- Definition of a unit of fishing effort for purse-seiners using DFADs that accounts for different factors influencing catchability,
- WP 2- Standardization of catch-per-unit-effort series of the EU purse seine fleet, for juveniles and adults of the three tropical tuna species and exploration of some FAD-regulations in management strategies,
- WP 3- Alternatives to CPUE,
- WP 4- Catch composition around FADs and estimation of potential effects on other marine organisms.

Right from the start of CECOFAD it was clear that transversal activities were required in addition to the four Work Packages to coordinate the technical aspects of the project. Given the importance of data management (definitions of variables, minimum data requirement and links between the various databases) these activities were grouped into a separate work package, WP5.

Because science-industry partnerships can improve the quality and availability of data and knowledge, the project research is fostering collaborative research between operators and scientists, without compromising the independence of the latter. CECOFAD is co-funded by EU-DG Mare, 3 scientific institutes (IRD, IEO and AZTI) and 3 professional tuna owner company associations (ANABAC, OPAGAC and ORTHONGEL). In order to bring the objectives and achievements of the project to the notice of a wide audience, a website (http://www.cecofad.eu/) was developed right from the start of CECOFAD. The website will be maintained for 2 years after the completion of the project.

1. Main results by working package

1.1. WP1: Definition of a unit of fishing effort for purse-seiners using DFADs that takes into account various factors affecting catchability

Until recently, the fishing effort for purse seine fisheries, dominated by sets on free-swimming schools (FSCs) and natural floating objects ("logs"), has been expressed as the daylight hours spent looking for visual cues of tuna schools minus the time taken for the set (i.e., the searching time). However, the increase in fishing efficiency due to new technologies that have been introduced (Gaertner and Pallares, 1998, Torres *et al.* 2014) and the use of drifting artificial fish aggregating devices (DFADs) since the early 1990s (Ariz *et al.* 1999; Hallier and Parajua, 1999) have broken the link between searching time and effective fishing effort for DFAD sets (Fonteneau *et al.* 1999). Remote detection of satellite-tracked dDFADs often allows purse seiners to move directly towards a buoy, sometimes at night, avoiding or significantly reducing searching time. In addition, the recent development of satellite-tracked echo sounder / fish finder units attached to floating objects (Moreno *et al.* 2007; Lopez *et al.* 2014) gives purse seiners real-time information about fish schools aggregating around DFADs and has resulted in an increasing proportion of successful DFAD sets. The use of supply vessels, which can visit DFADs and inform purse seiners on the fish aggregations around these DFADs, also contributes to the efficiency of some purse seiners (Arrizabalaga *et al.* 2001).

In addition to conventional data (logbooks, observer on boad, national FAD management plans), the tasks developed within the WP1 used various types of unofficial data, including: annual orders for various types of buoys, quarterly reports of buoy activation / deactivation and GPS buoy tracks, all of them for the French purse seiners, VMS for the French fleet and partially for Spain, as well as various surveys of French and Spanish fishermen.

Overview of skippers' perception of the changes in efficiency due to the new technologies

Various surveys were conducted to determine how tuna purse seiner skippers perceived the implementation of the new onboard technologies and the related benefits in terms of fishing efficiency. French and Spanish purse seine skippers operating in the Indian Ocean were questioned to determine their strategies regarding DFAD deployment, monitoring and fishing and their perception of the effect of the use of DFADs on their efficiency, in comparison with the use of other new fishing technologies (**Figure 1**). An independent survey conducted during an International Seafood Sustainability Foundation (ISSF) skipper workshops with skippers from the Spanish and associated fleets operating mainly in the Pacific Ocean were questioned on more than 100 aspects of the technology onboard (**Figure 2**). From both studies it was showed that most important factors in improving the fishing efficiency were the use of DFADs, specifically the total number of available DFADs at sea, GPS buoys, echo sounders buoys, and electronic equipment onboard. It should be stressed that the age of the vessel was not considered to play a major role in increasing fishing efficiency. This likely due to the fact that vessels tend to be repaired, maintained or checked every one or two years, which makes them highly dependent on the performance of the mechanical and electronic equipment onboard rather than their age.

Changes in fishing technology related to DFAD fishing

As already stated, various studies have described the introduction of new onboard technology for tuna purse seiners. However, this information was only qualitative. One of the main achievements of CECOFAD was to estimate the changes in the proportion of the various systems used for locating buoys at-sea by the French purse seiners in the Atlantic and Indian oceans, from HF radio / GPS to GPS / echo sounder buoys. A detailed description of these technological changes in locating systems is shown in **Figure 3** the Indian Ocean. The type of buoy used by French fishing companies changed on average every 2 years during the period 2002-2014, with one main model generally predominating each year. A similar pattern over time was observed for the French fleet operating in the Atlantic Ocean (**Figure 4**). Unfortunately this type of information was not available for the Spanish fleet and only guesstimates are available from past studies (**Figure 5**).

Another important aspect is the direct effect of the number of buoys deployed at sea on the total tuna catch per vessel. For the first time the relationship between the number of active DFADs and the catch per Spanish purse seiner (with or without the assistance of a supply vessel), per ocean and per quarter was explored in the Atlantic and Indian oceans. The size category of the purse seiner was also taken into account. On average, having a supply vessel allowed purse seiners to have more DFADs although some vessels seeded a relatively low number of DFADs (**Figure 6**). Other factors, not accounted for in this preliminary analysis, could explain the high variability observed in this figure, e.g., the type of echo sounder buoy, whether or not purse seiners from the same company shared all the buoys, the proportion of buoys stolen (this might be larger for purse seiners without supply vessels and it was suggested that the supply vessels might reduce theft).

Estimated number of DFADs and buoys at sea

Since the mid 1990s, the use of DFADs has increased considerably in tropical tuna purse seine fisheries. Furthermore, since the 2000s, purse seiners have been able to monitor both natural floating objects and DFADs with GPS buoys while they are drifting. This extensive use of DFADs and GPS buoys raises several concerns for tropical tuna stock assessment and management. It is particularly difficult to know how many DFADs and GPS buoys are in use, how purse seiners deploy new DFADs and GPS buoys and the proportion of the fishing effort spent on setting on DFADs and logs or on free schools. To address the question of how many DFADs and GPS buoy tracked objects are currently drifting in the Atlantic and the Indian Ocean, various complementary sources of information derived from declarations and observations at-sea were used. One source of unofficial data was based on historical purchase orders for buoys and declarations of activities related to DFAD activities by the French purse seiner fleet.

For the Atlantic Ocean, the number of buoys purchased and the quarterly information on the activation/deactivation provided by the satellite communications operators were used to estimate that each vessel purchased an average of 156 buoys in 2013, 90 of which were active (Goujon *et al.* 2015). It should be noted that French tuna-boat owners association limited the number of buoys purchased each year by each purse seiner to 200 and the number of active buoys to 150. For the Indian Ocean, Chassot *et al.* (2014) combined 3 three data sources to describe the use of DFADs and buoys by French purse seiners over the period 2002-2014: (1) records of buoy purchase orders provided by fishing companies, (2) satellite transmission metadata based on the quarterly reports produced by buoy supplier companies for each vessel, and (3) activities related to DFADs and buoys included in purse seiner logbooks from 2013 onwards. However, in order to use data that was comparable with that available for the Atlantic Ocean, only purchase order data was used. The number of buoys available for French purse seiners operating in the Indian Ocean increased by an average rate of about 10 per year over the period with the average number of buoys available per vessel increasing from 60 in 2002 to 200 in 2014 (**Figure 7**). It must be noted however that the number of active buoys per French purse seiner at the start of each quarter, as well as the average number of buoys that emitted a signal during each quarter, remained stable over the period 2010-2013 with the overall average number of buoys per French purse seiner being 89 (close to the estimate provided for the Atlantic Ocean). It should be stressed that, at the same time, there was an increase in the number of activations/deactivations, suggesting that the buoy utilization was dynamic to ensure the renewal of the DFAD standing stock for each vessel.

Data on the number of active buoys used by the Spanish purse seiners operating in the Atlantic and Indian oceans were collected within the framework of the Spanish DFAD management plan in 2013. This showed the considerable variability in the number of buoys used by purse seiners (**Figure 8**). For the Spanish fleet operating in the Atlantic Ocean, each purse seiner followed an average of 429 active DFADs per year (Delgado *et al.* 2015). However, as for the French purse seiners, this might give an overestimate of the total as some active DFADs were followed by more than one vessel and, might, therefore, be double counted. On average, 401 active DFADs were followed by each Spanish purse seiner operating in the Indian Ocean (Delgado *et al.* 2014). The average number of DFADs deployed by Spanish flag vessels was around 854 per year, if only purse seiners are considered (i.e., excluding support vessels).

The total number of DFADs deployed at sea in the Atlantic and Indian oceans over the last ten years was estimated from 2 different approaches, based on information provided by the French tuna association and extrapolated to the other purse seiner fleets.

The first approach was based on the number of active DFADs per vessel provided by the French tuna association, the catch per DFAD set and the total catch on DFADs for the various purse seiner fleets (**Table 1**). In the absence of data for the Spanish fleet at the time of the analysis, it was assumed that annual DFAD catches per vessel for the period 2004-2013 were proportional to the number of DFADs. The number of DFADs seeded by each Spanish purse seiner was estimated at an average of 2.5 times greater than for the average French purse seiner (as opposed to three times greater in previous studies). This method estimated the average number of DFADs for each Spanish purse seiner in 2013 at 385 DFADs, which is close to the number of 426 active DFADs seeded for each Spanish purse seiner estimated by Delgado et al (2015). No data was submitted to the ICCAT on the number of DFADs or buoys used by non-European fleets of purse seiners (Ghana, Cote d'Ivoire and Guinea). However, assuming that the average annual catch for each seeded DFAD was identical to the average annual DFAD catch for each buoy of the French and Spanish fleets, the number of DFADs seeded by these fleets was estimated from their total catches using DFADs. Based on these data and assumptions, the estimated total number of DFAD sets per year in the Atlantic Ocean by all purse seine fleets increased significantly from less than 7,000 DFADs before 2008, to 17,300 DFADs in 2013 (**Figure 9**). This corresponds to a 2.6 fold increase between the period 2004-2007 and 2010-2013.

For the Indian Ocean, the French DFAD database was extrapolated to give the total number of DFADS active in the Indian Ocean using the method described above for the Atlantic Ocean. Based on 2 assumptions (i.e., assuming each Spanish purse seiner could seed either 1.7 (RF1) more DFADs than a French purse seiner, or 3 (RF2) time more) the number of Spanish and Seychelles DFADs deployed per vessel and in total was tentatively estimated (**Figure 10**).

The second approach combined 4 different sources of data to evaluate the total number of DFADs and total number of buoys at sea: (1) GPS buoy tracks of the DFADs and logs followed by the French fleet, (2) quarterly French fishing company orders for buoys, (see **Figure 11** for the French fleet estimates only) (3) surveys of purse seine skippers and (4) observations of DFADs and logs by observers onboard French and Spanish purse seiner fleets. The proportion of buoys used on DFADs or logs as well as the proportion of French and foreign GPS buoys were estimated as follows (**Figure gure 12**).

After extrapolation to give the total number of DFADs and GPS buoys used by all purse seine fleets operating in the Atlantic and Indian oceans, the total number of DFADs used per day increased from 1,175 in January 2007 to 8,575 in August 2013 in the Atlantic Ocean and from 2,250 DFADs in October 2007 to 10,300 DFADs in September 2013 in the Indian Ocean (**Figure 13**).

Activities at sea and fishing strategies adopted by the EU tuna purse seine fishery

Data collected within the framework of the Spanish and French FAD National Management Plans were used to determine the proportion of time spent on the various activities carried out when using DFADs (deployment, visits, retrieval, changing buoys). As supply vessels provided valuable assistance, the activities of the Spanish purse seiners were compared in the Atlantic and Indian oceans with and without the support of a supply vessel (**Figure 14**). The proportion of time spent on each activity appeared to be specific to each ocean but in both cases, on average, the assistance of a supply vessel increased the amount of time spent on sets by 3-4 percentage points. As expected, deploying DFADs was the main role of Spanish supply vessels in the Atlantic and in the Indian oceans.

The activity pattern at-sea was also obtained from the French DFAD management plan but the lack of a common definition for each activity makes it difficult to compare the French and Spanish purse seiner fleets. Despite these limitations, it was observed that 63% of the activities of a French purse seiner were related to DFADs deployed by the same vessel against 36% for DFADs that had been deployed by other vessels and only 1% for DFADs without a radio beacon. The situation was different for logs of which 38% had been fitted with beacons by the same vessel and only 4% had been fitted with beacons by another vessel. 58% of the logs found at sea did not have beacons. Furthermore, whereas 8% of the visits to a DFAD did not result in a set, only 3% of the logs encountered did not result in a set (Goujon *et al.* 2014).

According to Spanish purse seiners, it was essential to have a good seeding strategy to increase fishing efficiency. The most common strategy was to alternate conventional buoys and echo sounder buoys during the seeding operation (Lopez *et al.* 2015). Nevertheless, these practices may change as the number of buoys equipped with echo sounders is expected to increase until echo sounders are used 100% by all vessels. The seeding strategy was based on zones for each season but was strongly affected by the number of DFADs deployed by other vessels DFAD that were encountered during fishing trips, the potential poaching rate within an area, the probability of finding free schools in the fishing zone, the financial resources of the fleet owner and/or the number of DFADs deployed by vessels of the same company, which sometimes shared fishing strategy and DFADs. The practice of sharing DFADs between vessels of the same company to reduce costs and increase the fishing rate varied between countries and ocean (this practice was more common in the Pacific Ocean where vessels must travel significant distances to reach the fishing areas (**Figure 15**).

From the analysis of the trajectories of the French drifting DFADs and the time spent at sea it was showed that on average, DFADs have a far longer time at sea in the Atlantic than in the Indian Ocean (**Figure 16**). During CECOFAD it was also showed that the time and distance between consecutive DFAD deployments were generally shorter for the Spanish fleet than for the French fleet (**Table 2**).

1.2. WP2 Standardization of catch-per-unit-effort series of the EU purse seine fleet, for juveniles and adults of the three tropical tuna species and exploration of some FAD-regulations in management strategies[6].

Reliable estimates of the catch per unit effort (CPUE) should consider the effective fishing effort, i.e. the amount of effort effectively deployed at sea to achieve the corresponding unit catch. The effective fishing effort is never measured in practice and must be estimated. In particular, there is no reliable abundance indicator for drifting artificial fish aggregating devices (DFADs) used by the tuna purse seine fishery. Application of statistics and numerical techniques have allowed fisheries scientists to develop models for standardizing CPUE that allow for the structure of fishery data, such as dependencies and missing values. Mixed models were developed for standardizing CPUE as they have been shown to deal with hyperstability and temporal autocorrelation issues (Nishida & Chen, 2004; Cao *et al.*, 2011). These models were extended to include factors relating to the longitudinal structure of the data, at the levels of vessels and skippers (Maunder & Punt, 2004; Campbell, 2015).

Based on the conclusions of the U.E. Research Project ESTHER (Gaertner and Pallares, 1998), for a better understanding on the specific impact of the new technologies introduced on board, the CPUE can be decomposed into several sub-indices (Chassot *et al.* 2012; Katara and Gaertner, 2014). Delta-lognormal models were developed for the standardization of the DFAD CPUE with the aim to separate (1) the probability of presence of bigeye tuna in the set and (2) the size of the catch where there was a positive set. Owing to the difficulty of gathering unofficial information, the standardization of CPUE was limited to juvenile bigeye caught using DFADs and to non-standard explanatory variables provided by the French fleet. Various conventional and unofficial candidate predictors were tentatively introduced in the standardization process (**Table 3**). For this reason, Lasso models were used to select the variables rather than standard variable selection methods, as there was a large number of initial variables which can lead to over-fitting and computational problems (Tibshirani, 1996, 2011). The GLMs were extended to GLMMs by treating the skipper and the vessel as crossed effects and the year - grid cell interaction as a random effect. Both GLMs and GLMMs were developed and the resulting standardized CPUE time series were compared (Katara *et al.* 2016). The process for the standardization of the CPUE is shown in **figure 17**. The analysis was repeated for the combined French and Spanish fleets but with a smaller number of predictors because data for the Spanish fleet was missing (**Table 4**). However the relevance of some non-traditional factors was highlighted, in particular the needs to collate the links between each supply vessel and its associated purse seiners and the number of active DFADs per vessel. It was also suggested that a factor which was non significant in a specific dataset (e.g., the number of DFAD per French vessel right censured to 200) could be significant for a larger dataset (e.g., including Spain for which the number of DFADs per vessel shows large variation, see **Figure 8**). Detailed results for the Lasso approach and fitted CPUE can be found in Katara et al (2016).

An attempt was made at the beginning of CECOFAD, based on a publication by Laurec (1977), to incorporate geographical distance into the standardization process. However, the results revealed no spatial organization and did not support the work that was originally planned. Consequently VMS data submitted on a quarterly basis by the French tuna association Orthongel were used to analyze the geographical distribution of DFAD sets in relation to the area covered by the fleet in the Indian Ocean for the period 2000-2012. Results suggest that the fishing power and capturability vary from quarter to quarter (Saulnier, 2014).

WP3- Alternatives to CPUE

Relative abundance indices based on CPUE data are notoriously problematic (Maunder et al., 2006), as catch data is usually biased by fishing effort, coverage and other limiting factors of fishery data. For this reason, one of the major features of the CECOFAD project was the exploration of alternative fishery-independent indices of the abundance of tuna and non-tuna species associated with DFADs. The CECOFAD project aimed to develop new methods for obtaining direct indices of tuna and non-tuna species abundances using (1) echo sounder buoys attached to DFADs and (2) behavioral models, calibrated using tagging data, representing the continuous process of association and disassociation, as well as the residence time under DFADs.

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[6] Notice that owing that the effects of certain DFAD regulations included in management strategies may impact on the whole ecosystem, this study initially scheduled as part of WP2 was transferred to the WP4 section of the document.

Data cleaning and modeling a Buoy-derived Abundance Index

Estimating the probability and abundance of tuna and non-tuna species directly using the information obtained from echo sounder buoy acoustic biomass data requires gathering, collating and processing a large dataset of heterogeneous echo-sounder buoy information and developing a methodology which considers all the factors for the standardization of the acoustic information. The information from the Spanish tropical tuna purse seine fleet operating in the Atlantic, Pacific and Indian Ocean was collected and loaded into a database for further processing. This database includes data on the major buoy manufacturers: Marine Instrument, Satlink, Zunibal, thus the sampling configuration (number of emitted pings, sampling duration, time of the day in which the acoustic sample is taken, etc.) and the technical specifications of the echo sounder buoys (beam angle, transducer frequency, etc.) depend on the model. This implies different units of measurements and outputs for different models of buoy, making it difficult to compare the raw acoustic samples and estimates of the different models easily (**Figure 18**).

The model proposed by Santiago et al (2016) is based in an assumption very similar to the fundamental relationship between CPUE and abundance, where CPUE is considered proportional to the abundance and catchability is the coefficient of proportionality. In our case, the signal from the echo sounder was assumed to be proportional to the abundance of fish.

$$BAI_t = \varphi \cdot B_t$$

where BAI_t is the Buoy-derived Abundance Index, φ is the coefficient of proportionality, and B_t is the abundance in time t.

Because the coefficient of proportionality φ is not constant, nominal measurements of the echo sounder buoy records were standardized using a Generalized Linear Mixed Modeling approach. Due to the significant proportion of records with zero abundance a delta-lognormal distribution (Lo et al., 1992) was used in the model to estimate BAI as the product of: i) the probability of finding tropical tuna in the acoustic observations (proportion of positives) and ii) the mean relative abundance where there was a positive observation.

Apart standard data cleaning carried out to remove outliers (invalid, impossible or extreme values) related to bad geolocation, time, or other factors, several criteria required for cleaning datasets before standardizing an abundance index derived from echo sounder buoy data were identified (**Table 5**). In addition to the traditional factors (year, month and area) the following parameters should be considered for the standardization of buoy derived abundance indexes: Soak time, Type of buoy, Frequencies at which buoys operate, Units provided by the buoy, Sampled volume, Acoustic filters automatically applied by the buoy, Depth of the acoustic layers, Bearing and speed of DFADs, Density of DFADs, Environmental variables, Species composition beneath DFADs.

Modeling the aggregation process of biomass under DFADs

Behavioral models representing the continuous process of association and disassociation, as well as the residence time under FADs, were also identified as an alternative to commercial catch data for estimating abundance. However, to date these behavioral models (e.g., Capello *et al.* 2015) have been used only to assess the proportion of the fish population associated with anchored FADs (AFADs). Because industrial purse seiners do not usually use AFADs, further research is required to determine the temporal and spatial dynamics of fish aggregations under DFADs.

WP4 Catch composition around FADs and estimate of potential effects on other marine organisms

DFAD characteristics, new materials and fishing practices

Characteristics of the DFADs were described based on information collected from skippers within the framework of the Spanish and French DFAD Management Plans:

1. surface structure with nets and bamboos,
2. surface structure with metal or PVC,

3. non-entangling DFADs: with the surface structure of the dFAD
   o not covered
   o only covered by non-meshed materials such as ropes or canvas sheet or
   o with netting rolled up and securely tied in "sausages" with nets of maximum 3 cm
4. natural objects,
5. unknown DFADs,
6. surface structure without net coverage or non-entangling coverage

In the case of the Spanish fleet, despite a large proportion of DFADs with unknown characteristics (approximately one third of the DFADs in the Atlantic and in the Pacific oceans), the decrease in the proportion of non-entangling DFADs used between 2013 and 2014 is due to the increase in DFADs without net coverage or non-entangling coverage. For the French fleet, Goujon et al (2014) reported that the first non-entangling designs were introduced in 2010 in the Indian Ocean and in 2011 in the Atlantic ocean. Since 2012, French purse seiners are authorized to deploy only non-entangling DFADs.

The ecosystem approach to fisheries aims to reduce by-catch mortality and so discarding practices have been introduced in the EU purse seine fleets. A manual has been drawn up and disseminated to increase the probability of survival for released fish and megafauna (Poisson et al., 2014). Observing good practices continues to be one of the objectives of the EU purse seine fleets as a means of reducing mortality of vulnerable species. For several Spanish vessels operating in the Atlantic Ocean, initial results showed significant improvement in shark release conformity between consecutive fishing trips (Goñi *et al.* 2015). These results should be validated using scientific observer data to determine any potential bias in skippers' reports. However, they are encouraging in terms of correct fauna release operations as well as in improvement made by individual vessels during consecutive fishing trips.

Impacts of lost DFADs

French GPS buoy trajectories were analyzed to detect DFAD beaching events and the potential damage to fragile coastal ecosystems. A beaching event was defined as the same position repeated at least three consecutive times with the location a long way from a port (more than 10 km) and close to the coast (less than 5 km). It was showed that for the period 2007-2013, around 10% of the trajectories of floating objects with GPS-buoys ended with a "beaching event" in the Atlantic and Indian Oceans, suggesting that 1,500-2,000 may be lost onshore each year, with significant portions of these beaching events occurring in areas that might have sensitive habitats, such as coral reefs. In the Atlantic Ocean, beaching events tend to be concentrated in the Gulf of Guinea but some buoys travel across the ocean and beach on the Brazilian coast (**Figure 19**). In addition, observations showed that non-entangling DFADs with 'sausage nets' still entangled sea turtles when they beached on coral reefs.

Exploration of some FAD regulations in management strategies

It is commonly accepted that fisheries have a direct impact on the whole of the marine ecosystem and, for this reason, the Ecosystem Approach to Fisheries (EAF) is being promoted as a framework for sustainable development, recognizing the interdependence between human well-being and ecosystem health (Garcia et al. 2003). However, although this approach is generally accepted, the types of action needed to set up EAF management plans are not considered as main priorities by the tRFMOs. As an example time-area moratoria on DFADs have been adopted regularly by tuna RFMOs since the mid 1990s, but these measures are limited to the protection of juvenile tuna and do not take account of the potential impact on bycatch or associated megafauna (whales and whale sharks).

A simple iterative "fishing-day" model was developed to investigate the consequences on tropical tuna and bycatch of introducing wide area, six-month moratoria on DFAD sets (**Figure 20**). The "fishing-day" model took account of the probability of the occurrence of several different fishing events (such as visual cues, size and species of tuna school, etc) and skippers' on-the-spot decisions based on European purse-seine fishery data for the period 2005–2014 (Escalle et. al., 2017). Monte Carlo simulations were carried out 1000 times to examine various scenarios for reallocating the fishing effort or changing fishing practices following the introduction of a six-month moratorium on DFAD sets for the European purse-seiners. The simulations included realistic scenarios in terms of difference in fishing strategies (e.g., DFAD targeting as observed for the Spanish fleet or combining DFAD and free schools fishing as seen for the French fleet) and reallocation of the fishing effort (e.g., at the periphery of the regulated area or towards the historic best fishing grounds).

As expected, for both the Atlantic and Indian oceans, the models predicted a decrease in DFAD sets and an increase in free school sets (**Figure 21**). As a consequence, the catch of small tuna (<10 kg) decreased (except for the French fleet in the Atlantic Ocean) while the catch of large tuna (≥10 kg) increased, leading to an overall decrease in tuna catch of ~100 t/yr/boat in the Atlantic Ocean and 600–1800 t/yr/boat in the Indian Ocean. The bycatch for all groups considered (other bony fishes, billfishes, sharks and turtles) decreased, except in the Atlantic Ocean, where the turtle and shark bycatch increased slightly for both fleets.

Effects of FAD fishing on emblematic and vulnerable species as well as on the Ecosystem

Concerns over the incidental capture of pelagic sharks has been the subject of several regulatory measures in tuna RFMOs (ICCAT-Rec [11-08], IOTC-Res [13_06], IATTC-Antigua convention), specifically because these species regularly become entangled in the netting that hangs below the DFADs. From observer-at-sea data collected by IEO and AZTI in the period 2003-2015, combined with the EU Copernicus data base for environmental data, a preliminary analysis used a delta-lognormal approach to characterize relevant environmental factors conditioning the habitat of silky sharks in the Atlantic and Indian oceans. However, due to time constraints, only an exploratory analysis was performed (**Figure 22**).

The bycatch data collected under the European observer programs in the Indian, Pacific and the Atlantic Oceans between 2003 and 2010 were used to assess the effect of FAD-fishing in terms of alpha and beta diversity, rarefaction curves and biomass metrics. Regional differences were identified but the species diversity associated with the DFADs was found to be richer than for free school sets. The species composition and the structure of the community were directly related with the fishing mode (**Figure 23**) and the environment in which the species lived. Diversity was explained by surface currents, wind patterns and upwellings at global scale, and by front systems, domos and eddies for both fishing modes at local scale. French observer datasets in the Atlantic and Indian oceans (2006-2013) also used in a similar approach but at a smaller scale. Rarefaction curves confirmed that the number of taxa under DFADs was higher than for free school sets in both oceans. Simpson diversity and evenness were also significantly higher using DFADs rather than free school sets in both oceans. The overall size spectra of the bycatch showed no significant difference between oceans but there were more small individuals using DFADs (Widehem, 2015).

WP5-Data Management

One of the challenges of the CECOFAD research project was to provide links between the various sources of information (logbooks, observer data, VMS, echo sounder data, etc) collected in the work packages. Another important aspect was the absence or imprecision of FAD-fishing activity data which should be incorporated into records in ERS or paper logbooks in the future.

Links between databases

One of the challenges of the CECOFAD project was to create bridges between the various datasets (logbooks, observer programs, sampling in ports, etc). The two databases *Balbaya* (information declared in logbooks) and *ObsTuna* (on board observer data), collected within the Data Collection Framework (DCF) by the Tropical Tuna Observatory of IRD (OT-IRD) for French purse seiners were linked using the Standard Data-Exchange Format[7], a human-readable file format for samplings, landings and effort data from commercial fisheries currently used within the EU DCF context (**Table 6**). This format allows a data aggregation level which is as low as possible while respecting data confidentiality issues and consequently should be considered as a good natural candidate for the exchange of data between partners in the tropical tuna fishery research community.

Floating object data model for fishing logbook and on-board observer data

One task of CECOFAD was to review the definitions of variables required for evaluating DFAD-fishing activities that should be continuously recorded in logbooks. On the basis on the most recent recommendations from tRFMOs (ICCAT and IOTC), the original electronic fishing logbook data model (ERS) was extended to floating objects and then updated to meet IATTC and WCPFC recommendations. The format may differ slightly between the French and Spanish fleets but it was considered very important to have an agreement covering the minimum data requirement and the meaning of the variables collected.

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[7] Jansen, T. (Ed). 2009. Definition of Standard Data-Exchange Format for Sampling, Landings, and Effort Data from Commercial Fisheries. ICES Cooperative Research Report No. 296. 43 pp. This should not be confused with the American SDEF data exchange standard.

In order to clarify certain definitions and to harmonize FAD data requirements between EU purse seine fleets, it was agreed that the information to be collected should:

(1) measure the fishing effort,
(2) measure the extent of changes in habitat caused by floating object fishing activities and
(3) measure potential pollution (plastics, bamboo, netting, metal).

A floating object data model for the fishing logbook and on-board observer data was drawn up on the basis of these three objectives. The first point concerns the definition of the floating object[8]. A floating object at sea (FOB) is defined as a FAD (Fish Aggregating Device) if it is a man-made FOB specifically designed to encourage fish aggregation at the device, while any FOB other than a FAD, i.e. a natural (branches, carcasses, etc) or artificial (wreckage, nets, washing machines, etc) object will be termed a LOG. FADs and LOGs are then broken down into different categories depending on their features. In the case of logbooks the new information to be collected can be summarized as described in **Table 7**.

The activities of the purse seiner associated with a FOB were defined as follows (**Table 8**). In order to improve the quality of data collected by the skippers, a "User Interface" (UI) could be developed with the collaboration of the skippers. For example, a droplist with each operation being clearly represented by a photo might be proposed. For a quick implementation of the floating object model in the logbook it might be relevant to discuss this UI with some skippers. For data collected by on-board observers, several properties of the floating objects were added to the form in order to comply with the recommendations of the tuna RFMOs on FOB/FAD data (**Table 9**).

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[8] Note: adding a beacon to a DFAD or LOG does not change its type. The main function of a buoy is to locate the FOB and estimate the aggregate biomass.

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Table 1. Number of DFADs used by French purse seiners in the Atlantic Ocean : seeded per year and DFADs active within a quarter, number of purse seiners and total catches using DFADs (Fonteneau *et al.* 2015).

	Nb of Active buoys/PS	Nb buoys seeded yearly/PS	Ratio Nbs FAD Seeded & active	Nb French PS	Average Nb of active FADs	Total Nb of seeded buoys yearly	Yearly FAD catches France	Average Catches on FAD by each PS	Average catch per buoy seeded yearly
2004		41		13		533	20 246	1557	38,0
2005		41		9		369	13 531	1503	36,7
2006		47		7		329	5 178	740	15,7
2007		42		5		210	4 453	891	21,2
2008		54		7		378	3 044	435	8,1
2009		60		10		600	7 552	755	12,6
2010	68	72	1,05	10	683	720	16 125	1613	22,4
2011	71	82	1,16	9	635	738	13 195	1466	17,9
2012	96	118	1,23	9	861	1062	16 956	1884	16,0
2013	90	156	1,74	9	808	1404	16 749	1861	11,9
2014		200		9		1800			
Average 2004-2013		71		9	747	634	11703	1270	20,0
Average 2010-2013	81	107	1,30	9	747	981	15756	1706	17,0

Table 2. Time and distance between consecutive DFAD deployments for Spanish and French purse seiners (Maufroy *et al.* 2014).

Purse seine fleet	Time (min)	Distance (km)
France	82.4	57.1
Spain	63.2	24.2

Table 3. Predictors used in the elastic net GLMs and the Lasso GLMMs (Katara *et al.* 2016). The numbers of positive and null fishing sets are used as predictors in the lognormal models.

Variables	Short description
Year Month	
Time at Sea Fishing Time	Duration of the fishing trip Duration of the fishing sets
Sample Area EEZ Grid Cell	Areas covered by the landing samples Exclusive Economic Zone 1° x 1° cell
Skipper Vessel Vessel age Vessel length Vessel power Vessel capacity Vessel category	Name of the skipper on each vessel and trip Vessel identifier Year vessel entered service In meters In horsepower In tonnage Vessel category based on vessel length and capacity
YFT price SKJ price YFT/SKJ price ratio	Yellowfin tuna price at Bangkok auction Skipjack tuna price at Bangkok auction Ratio between yellowfin and skipjack tuna prices
GPS buoys bought per vessel HF-GPS buoys bought per vessel HF-GPS/GPS buoys bought per vessel	The data on GPS, HF-GPS, and HF-GPS/GPS buoy purchases is only available for a small number of vessels
HF buoys deployed per vessel BS buoys deployed per vessel BSE buoys deployed per vessel	Parameters from Goujon et al 2014 (BSE = echo sounder buoy)
Distance of fishing set from a FAD	Distance of a set from the nearest FAD (monthly average)
Distance of fishing set from the centre of the FAD area	Distance of a set from the centroid of the FAD area (monthly average)
FAD counts around fishing set in a fixed (143 nm) buffer zone	Number of FADs around a fishing set. 143nm is the nearest neighbor distance between sets and FADs occurring in a given month, averaged over the time series.
FAD counts around fishing set in a variable buffer zone	Number of FADs around a fishing set. The buffer zone is equal to the maximum nearest neighbor distance between the fishing sets and the FADs for the given month.
FAD area	Total area occupied by FADs: the sum of the areas of the polygons of the standard distance for each FAD trajectory. Overlapping polygons were merged.

Table 4. Lasso GLMMs for the French fleet and the combined Spanish and French fleets (Katara *et al.* 2016).

	French Fleet			Spanish and French Fleets	
	Pr(C_s>0)	Lognormal		Pr(C_s>0)	Lognormal
Year	(f)	(f)			
Month			Year	(f)	
Time at Sea			Month	(f)	
Fishing Time			Time at Sea	3.5e+09	5.7e-14
Positive sets			Fishing Time	-8e+09	7.05e-14
Null sets			Positive sets		
Sample Area		(f)	Null sets		
EEZ		(f)	Total Sets		
Grid Cell			Sample Area	(f)	(f)
Skipper	0.65	0.001	Flag		
Vessel	0.49	0.1	Fleet	(f)	(f)
Vessel age			# of supply vessels (annual)	-5e-01	8.5e-13
Vessel length			EEZ	(f)	(f)
Vessel power			Grid Cell:year	0.9	0.459
Vessel capacity			Vessel		0.22
Vessel category			Vessel age	-7e+08	-3.7e-14
YFT price		-1e-14	Vessel length	9.8e-01	-6.9e-13
SKJ price		-4e-16	Vessel power	4.7e+09	-7.2e-13
YFT/SKJ price ratio			Vessel capacity	4.8e+09	-7.99e-13
GPS buoys bought per vessel			Vessel category	(f)	(f)
HF-GPS buoys bought per vessel			YFT price	-2.6e-01	-8.6e-14
HF-GPS/GPS buoys bought per by vessel			SKJ price	-1.5e-01	-1.5e-13
Number of HF buoys deployed per vessel	-0.08	9e-15	YFT/SKJ price ratio		-4.2e-14
Number of BS buoys deployed per vessel			Number of HF buoys deployed per vessel	2e-01	-8.6e-14
Number of BSE buoys deployed per vessel		-8e-16	Number of BS buoys deployed per vessel		
Distance from a FAD		-5e-02	Number of BSE buoys deployed per vessel	-2e+08	1.06e-14
Distance from the centre of the FAD area			Distance from a French FAD	9e-02	3.1e-13
FAD counts in buffer zone = 2.39dd			Distance from the centre of the French FAD area	6.6e-02	3.4e-13
FAD counts in buffer zone = max			French FAD counts in buffer zone = 2.39dd	-5e-02	3.4e-13
FAD area			French FAD counts in buffer zone = max	4e-02	-1.18e-13
Year*month			French FAD area	-2.6e-01	-8.6e-14
Year*Cell	1.76	0.5	Year*month		
Year*vessel age*category			Year*vessel category		

Table 5. Criteria that should be used for cleaning the datasets before standardizing an abundance index derived from echo sounder buoy data (Santiago *et al.* 2016).

Data cleaning	Objective
Time after deployment or after a set (<2 days)	Shorter time at sea may cause noise in the final estimate
Layer (<25 m)	To eliminate noise from non-tuna species associated with the DFAD
Time of day	Selecting only acoustic data at a common standard time could reduce the effect of local time
Bottom depth (< 200 m)	To eliminate acoustic records of FADs that have drifted into coastal areas and might provide false positives
Speed of the buoy (> 3 knots)	To eliminate records when DFADs are still onboard

Table 6 Main variables and metrics of the French DCF dataset in Standard Data-Exchange Format (e.g., bridges between Balbaya and Observ databases, Billet pers. comm..)

Level	Main variables
Trip	Sampling type (market, onboard, etc..) Vessel ID (encrypted) Vessel size Days at sea
Fishing operation	Date Time: 100% for onboard observer dataset and 30% for on-shore Location School type: free or log for on-shore, detailed for onboard (free, DFAD, whale, Whale-shark)
Species caught	Species Landed / discard Fate of discards: alive or dead (for onboard dataset) Catch weight Sampled weight
Size structure	Length class Number at length

Table 7. Codes, names and examples of different types of floating object that should be collected in the fishing logbook as a minimum data requirement.

Code	Name	Example
DFAD	Drifting FAD	Bamboo or metal raft
AFAD	Anchored FAD	Very large buoy
FALOG	Artificial log resulting from human activity (and related to fishing activities)	Nets, wreck, ropes
HALOG	Artificial log resulting from human activity (not related to fishing activities)	Washing machine, oil tank
ANLOG	Natural log of animal origin	Carcasses, whale shark
VNLOG	Natural log of plant origin	Branches, trunk, palm leaf

Table 8. Names and description of the activities related to floating objects and buoys that should be collected in the fishing logbook as a minimum data requirement (codes are not listed here).

	Name	Description
FOB	Encounter	Random encounter (without fishing) of a log or a FAD belonging to another vessel (unknown position)
	Visit	Visit (without fishing) of a FOB (known position)
	Deployment	FAD deployed at sea
	Strengthening	Consolidation of a FOB
	Remove FAD	FAD retrieval
	Fishing	Fishing set on a FOB[9]
BUOY	Tagging	Deployment of a buoy on FOB[10]
	Remove BUOY	Retrieval of the buoy equipping the FOB
	Loss	Loss of the buoy/End of transmission of the buoy

Table 9. FOB/FAD information added to observer onboard form to comply with RFMOs recommendations.

Properties	DFAD	AFAD	HALOG	FALOG	ANLOG	VNLOG
FOB built using biodegradable materials (true/false/undefined)	X	X	X	X		
FOB is non-entangling (true/false/undefined)	X	X	X	X		
Meshed material (true/false/undefined) in FOB	X	X		X		
Size of largest mesh (in millimeters)	X	X		X		
Distance between the surface and the deepest part of the FOB (in meters)	X	X	X	X		
Approximate surface area of the FOB	X	X	X	X		
Specifies the FOB's ID whenever present	X	X	X	X		
Fleet owning the tracking device / echo sounder buoy	X	X	X	X	X	X
Vessel owning the tracking device / echo sounder buoy	X	X	X	X	X	X
Anchorage type used for mooring (AFAD registry)		X				
Radar reflectors (presence or not) (AFAD registry)		X				
Lighting (presence or not) (AFAD registry)		X				
Visual range (in nautical miles) (AFAD registry)		X				
Materials used for the floating part of the FOB (list to be defined)	X	X	X	X		
Materials making up the FOB underwater structure (list to be defined)	X	X	X	X		
Tracking device TYPE+ID if possible, otherwise no or undefined.	X	X	X	X	X	X

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[9] A fishing set on a FOB includes two aspects: fishing after a visit to a vessel's own FOB (targeted) or fishing after a random encounter of a FOB (opportunistic).
[10] Deploying a buoy on a FOB includes three aspects: deploying a buoy on a foreign FOB, transferring a buoy (which changes the FOB owner) and changing the buoy on the same FOB (which does not change the FOB owner).
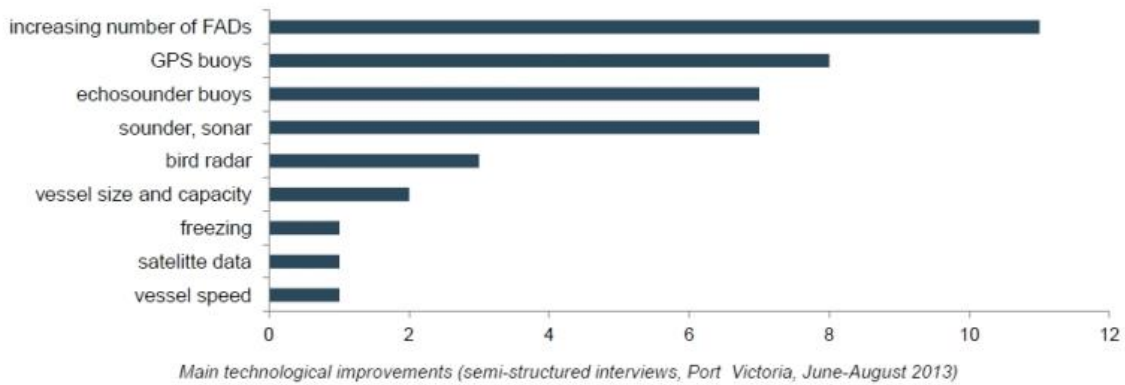
Figure 1. Technological improvements in fishing efficiency established from interviews with EU purse seiner skippers operating in the Indian ocean (Maufroy, 2016)
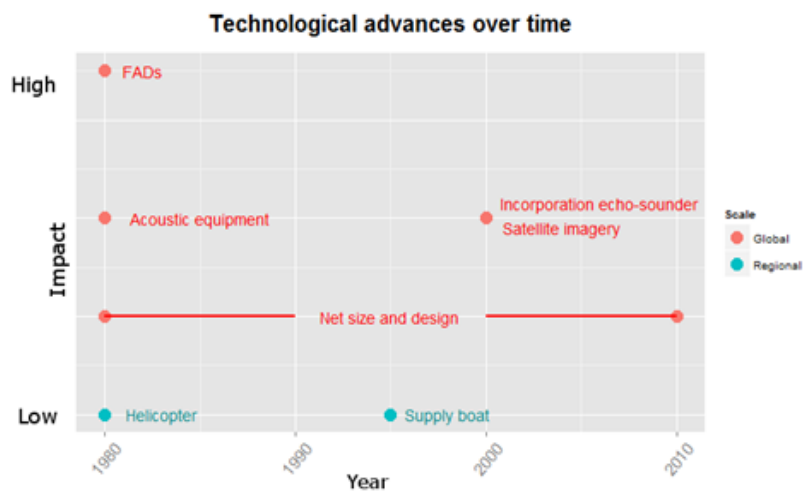
Figure 2. Historical changes in fishing technology among those with major effect on fishing efficiency of purse seine vessels over recent decades from ISSF Spanish skipper workshops. Factors not included here were considered to have a marginal effect on fishing capacity. (Lopez *et al.* 2015).
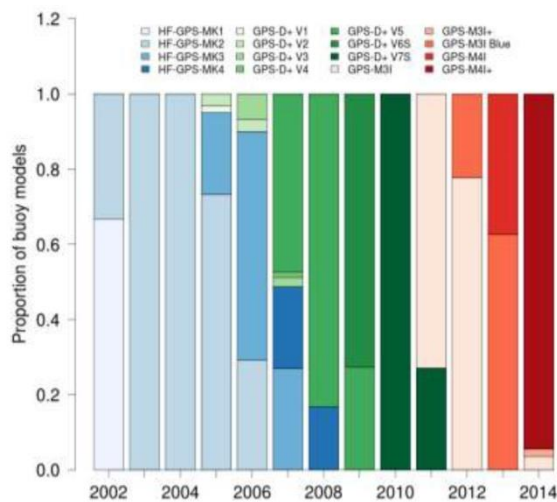

Figure 3. Proportion of buoys by type for a French fishing company the during the period 2002-2014 (Chassot *et al.* 2014).
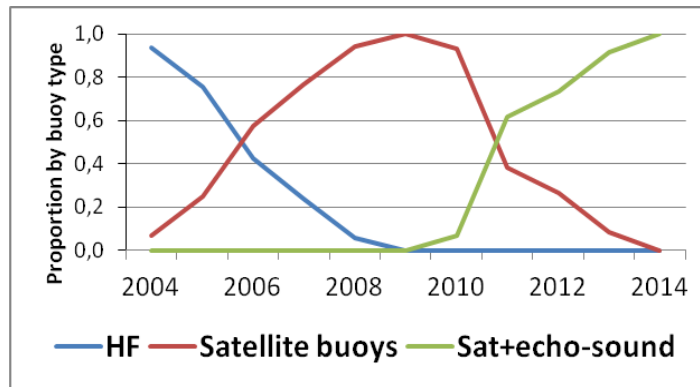
Figure 4. Transition from HF buoys to GPS buoys equipped with echo sounder for the French fleet operating in the Atlantic Ocean (from table 5 in Goujon *et al.* 2015).
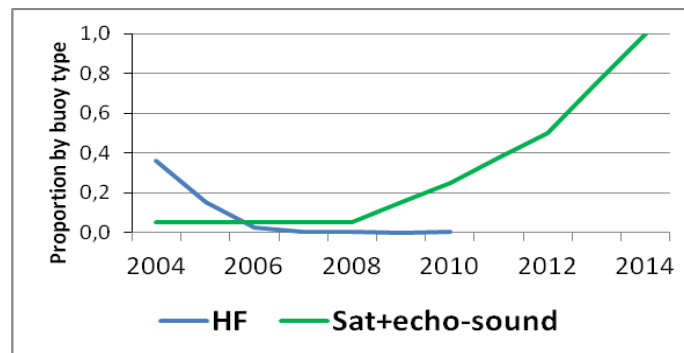
Figure 5. Guesstimates for the transition to most modern buoys for the Spanish (taken from Ramos *et al.* 2010 and Lopez *et al.* 2014).
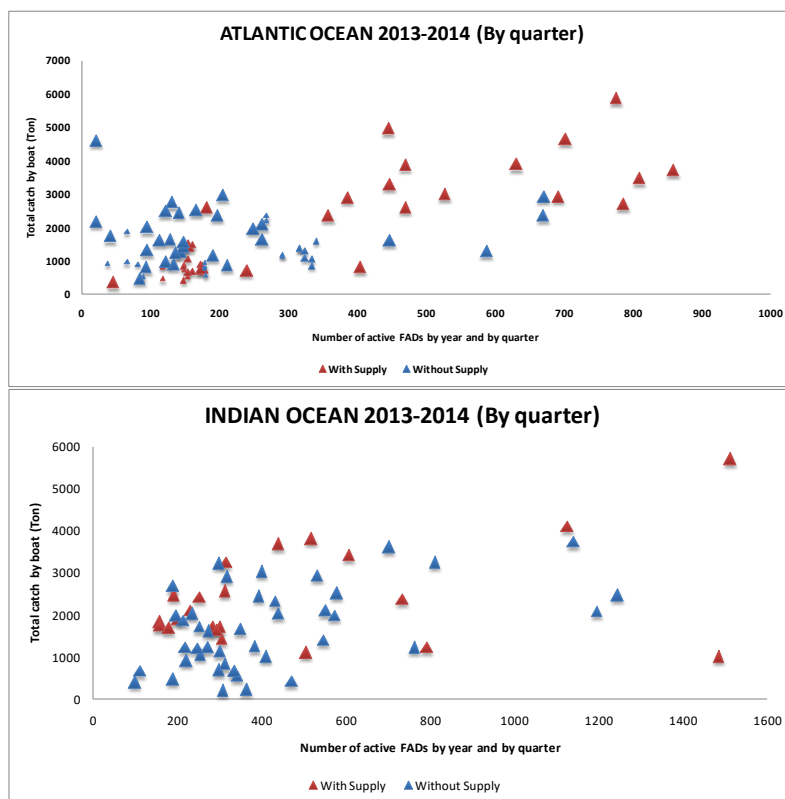
Figure 6. Relationship between the quarterly catch (all species combined) for each Spanish purse seiner and the number of buoys used in the Atlantic Ocean (top) and in the Indian Ocean (bottom) with a supply vessel (red) and without (blue); small purse seiners are represented by smaller triangles (Sotillo *et al.* pers. comm.).

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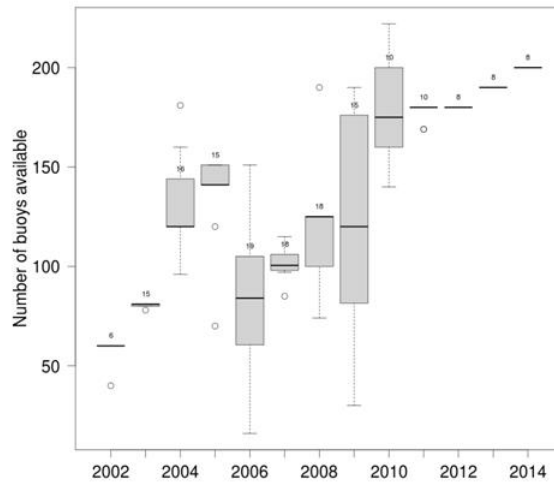
Figure 7. Annual number of buoys available per French purse seiner during the period 2002-2014 (Chassot *et al.* 2014); Numbers indicate the number of vessels for which data were available.
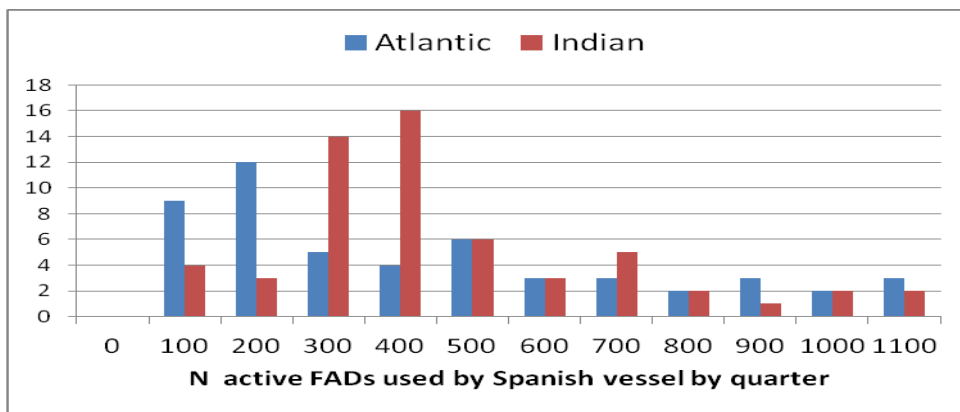
Figure 8. Number of active buoys equipped with DFADs used by the Spanish fleets operating in the Atlantic and Indian oceans in 2013 (taken from Delgado *et al.* 2014, 2015).
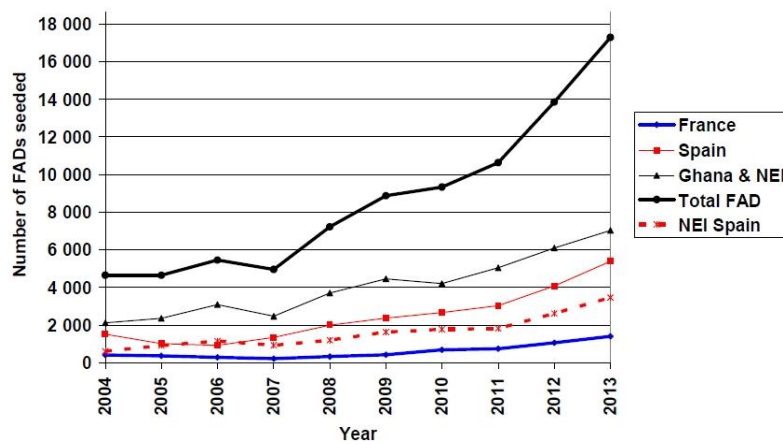
Figure 9. Estimated number of DFAD sets seeded per year for each flag and the total for the Atlantic Ocean (Fonteneau *et al.* 2015) NEI is "Not Elsewhere Included" for unreported catches.
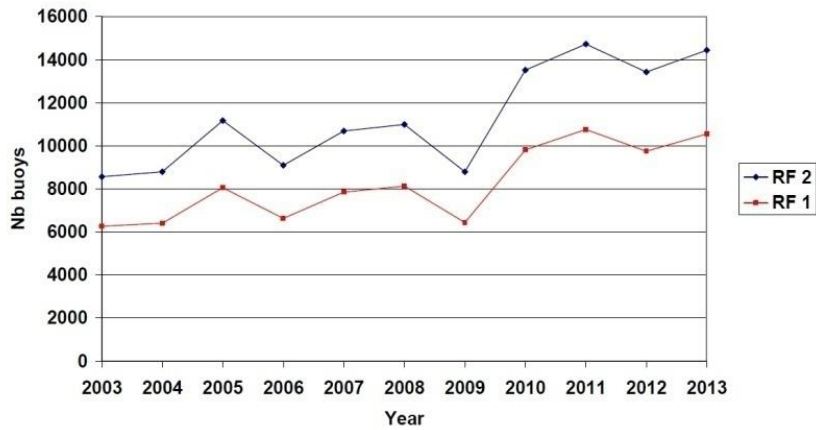
Figure 10. Total of the average catch per buoy per year observed for French purse seiners and estimated for the combined Spanish and Seychelles purse seiner fleets (based on assumptions RF1 and RF2) in the Indian Ocean (Fonteneau and Chassot, 2014).
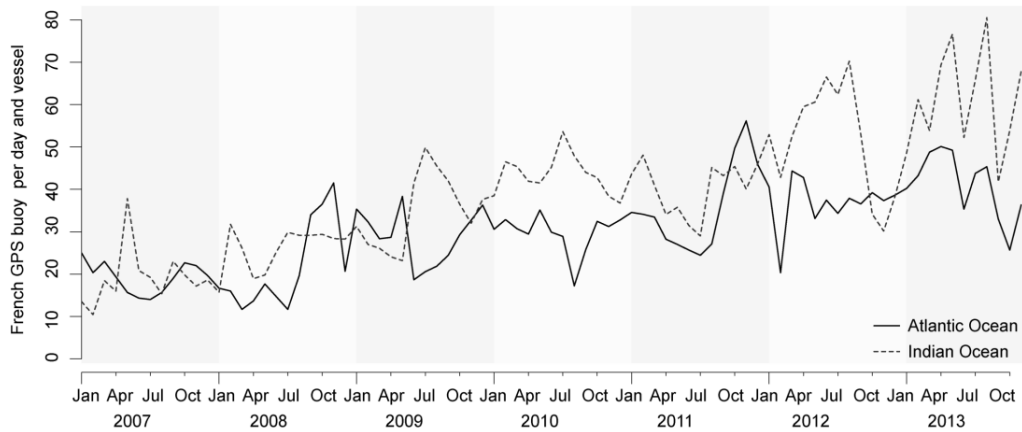
Figure 11. French GPS buoys per vessel per day in the Atlantic and Indian oceans based on GPS buoy tracks and orders provided by the French fishing companies (Maufroy, 2016).
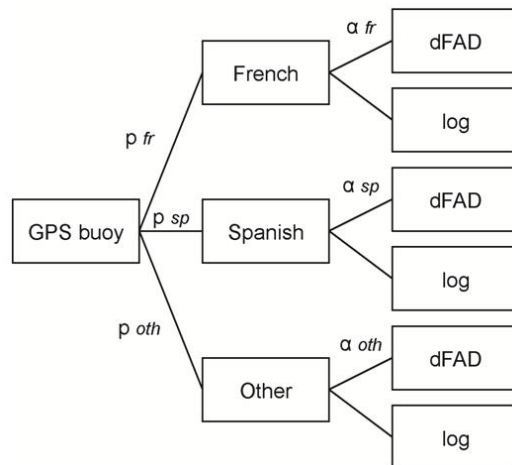
Figure 12. Extrapolation process used to estimate the total DFADs and floating objects (Maufroy *et al.* 2014).
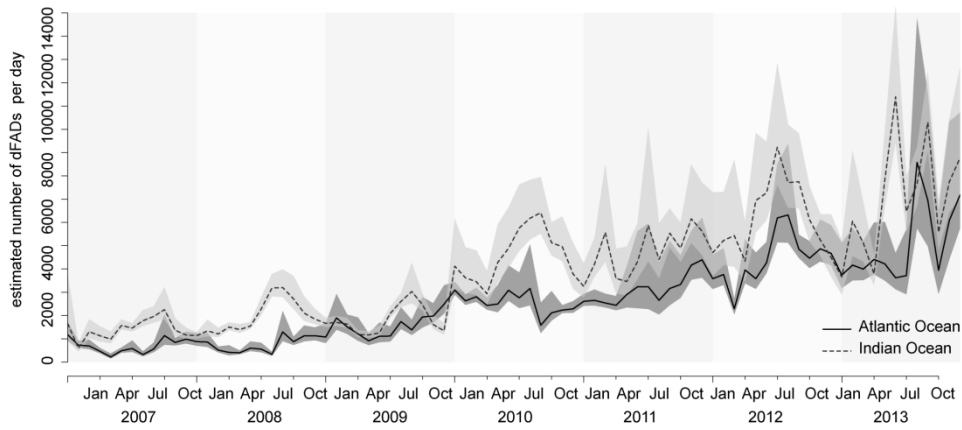
Figure 13. Estimates of the number of DFADs drifting at sea in the Atlantic and the Indian oceans (Maufroy, 2016).
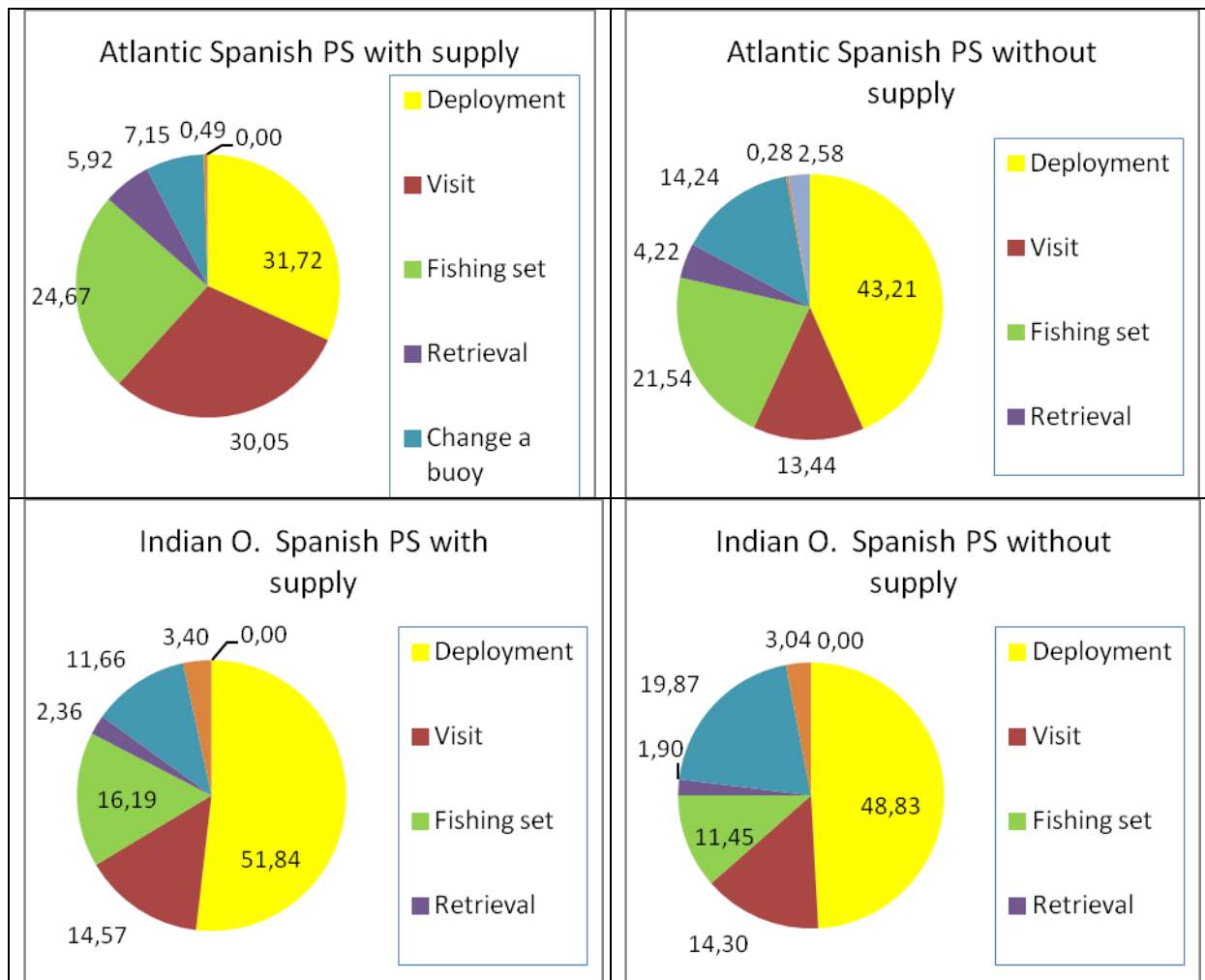
Figure 14. Proportion of time spent on fishing activities of the Spanish purse seiners with (left) and without (right) the assistance of a supply vessel in the Atlantic ocean (top) and in the Indian ocean (bottom); taken from Sotillo *et al.* pers. comm.; (2013 and 2014 combined).
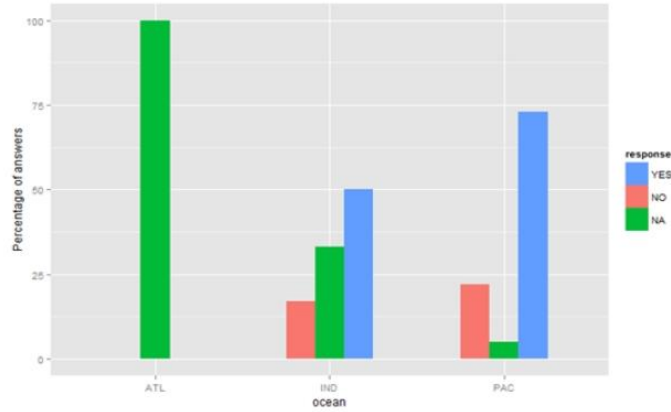
Figure 15. Sharing DFADs between Spanish purse seiners (on the X axis, in the Atlantic, Indian and Pacific oceans, respectively; Lopez *et al.* 2015).
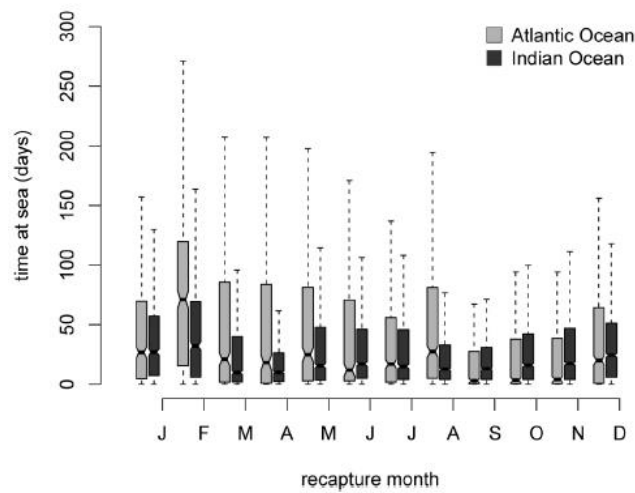
Figure 16. Time at sea for DFADs for each ocean and each month of the year for the French fleet operating in the Atlantic and Indian oceans (Maufroy *et al.* 2015a).
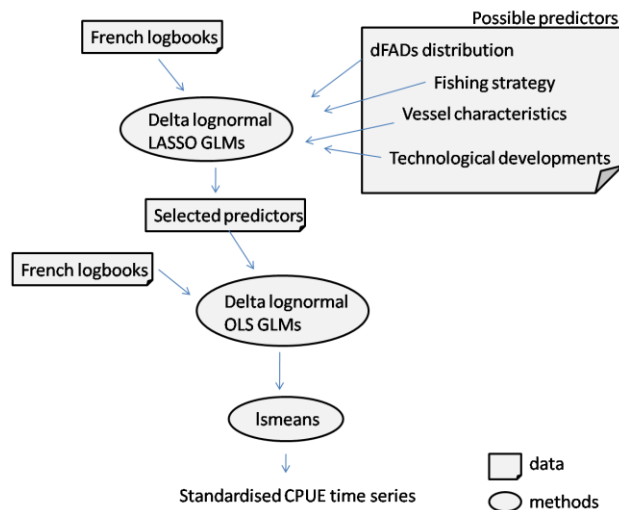

Figure 17. Process for the standardization of EU bigeye DFAD CPUE (Katara *et al.* 2016).
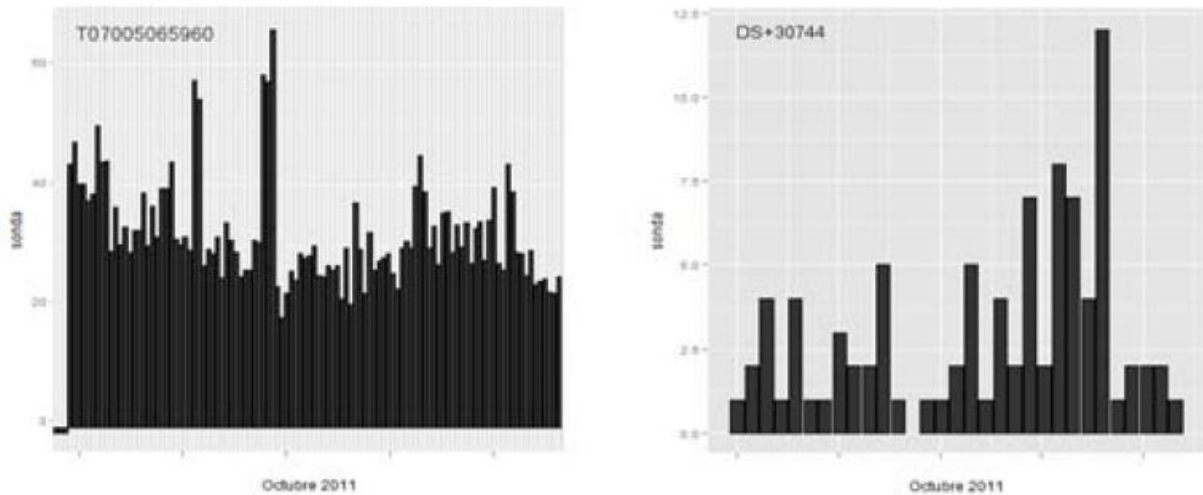
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Figure 18. Examples of acoustic time series recorded by a Zunibal (left) and a Satlink (right) buoy in the Indian Ocean in October 2011. The Y-axis represents the number of pixels occupied by the acoustic signal for the Zunibal buoy and tons of acoustic target for skipjack tuna for the Satlink buoy.
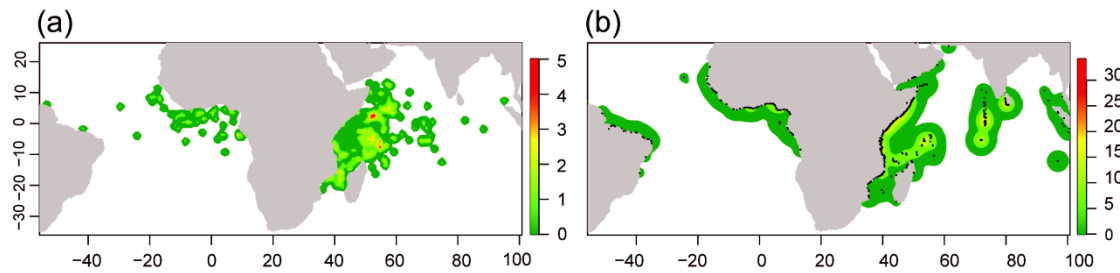

Figure 19. Smoothed densities of DFAD beaching events (b) and their deployment positions (a); black dots correspond to individual beaching positions (Maufroy et al. 2015a).
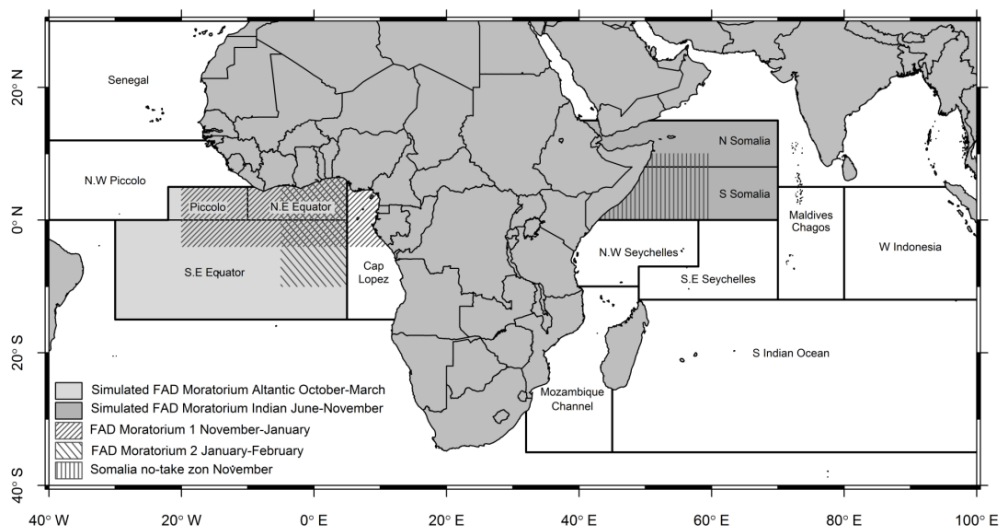

Figure 20. Examples of different six-month moratoria on DFADs used in the Monte Carlo simulations (Escalle, et. al., 2017).

Atlantic Ocean

Fleet	FAD	Free school	Whale	Whale shark	< 10kg	≥ 10kg	Total	Other fishes	Billfishes	Sharks	Turtles
		SETS				Tuna Catch			By Catch		
FR	↓	↑	=	=	↑	↑	↑	↓	=	↑	↑
SP	↓	↑	=	=	↓	↑	↓	↓	↓	↑	↑

Indian Ocean

Fleet	FAD	Free school	Whale	Whale shark	< 10kg	≥ 10kg	Total	Other fishes	Billfishes	Sharks	Turtles
		SETS				Tuna Catch			By Catch		
FR	↓	↑	↑	↑	↓	↑	↓	↓	↓	↓	↓
SP	↓	↑	=	↑	↓	↑	↓	↓	↓	↓	↓

Decrease total tuna catch : slight in the Atlantic (100), 600-1800 t in the Indian Ocean

Figure 21. Monte Carlo simulations for the main scenarios of six-month moratoria on DFADs in the Atlantic and Indian oceans (Escalle, et. al., 2017).

Figure 22. Spatial distribution of the silky shark Carcharhinus falciformis from Spanish scientific observer data (free schools and DFADs; Lopez et al pers. comm.).
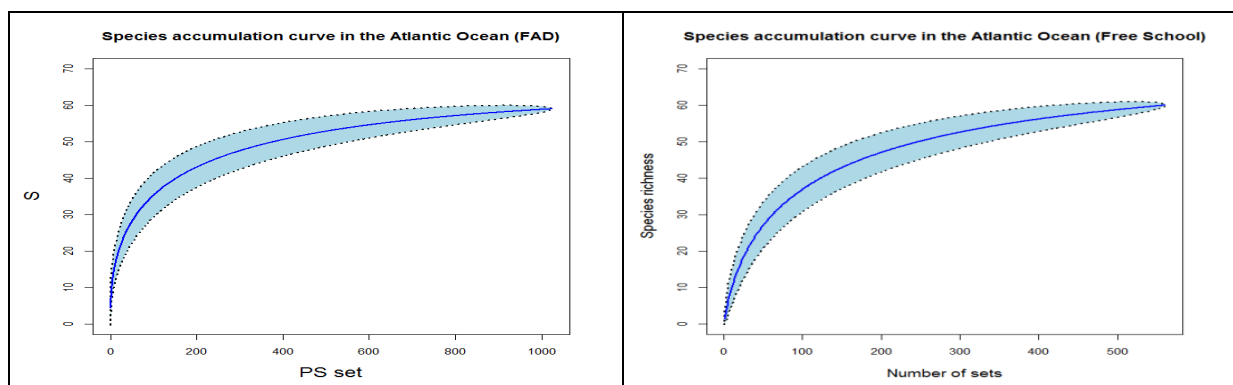
Figure 23. Species accumulation curves for bycatch in DFADS (left) and free school sets (right) in the Atlantic ocean, respectively (Lezama-Ochoa, 2016).